

Vectron International**Filter specification****TFS 666****1/5****Measurement condition**

Ambient temperature (T_0):	23	°C
Input power level:	0	dBm
Terminating impedance:		
Input:	50	Ω
Output:	50	Ω

Characteristics

Remark:

The maximum attenuation in the passband is defined as the insertion loss a_e . The nominal frequency f_N is fixed at 666 MHz without any tolerance or limit. The values of absolute attenuation a_{abs} are guaranteed for the whole operating temperature range. The frequency shift of the filter in the operating temperature range is included in the production tolerance scheme.

D a t a		typ. Value		tolerance / limit	
Insertion loss within PB	a_e	2.0	dB	max.	3.0 dB
Nominal frequency	f_N	-		666	MHz
Passband	PB			$f_N \pm 12$	MHz
Absolute attenuation	a_{abs}				
$f_N \pm 80$ MHz ... $f_N \pm 149$ MHz		51	dB	min.	33.5 dB
$f_N + 149$ MHz ... $f_N + 300$ MHz		47	dB	min.	45.0 dB
1 MHz ... 200 MHz		58	dB	min.	50.0 dB
200 MHz ... $f_N - 149$ MHz		67	dB	min.	55.0 dB
Group delay ripple within PB	p-p	10	ns	max.	0.2 μ s
IIP3	*	-		min.	36 dBm
Input power level		-		max.	10 dBm
Operating temperature range	OTR	-		- 10 °C ... + 75 °C	
Storage temperature range		-		- 40 °C ... + 85 °C	
Temperature coefficient of frequency	TC_f **	-76	ppm/K	-	

*) $f_{in1} = f_C - 14$ MHz; $f_{in2} = f_C - 14.4$ MHz; $P_{in} = 0$ dBm; $f_{measurement1} = f_C - 13.6$ MHz; $f_{measurement2} = f_C - 14.8$ MHz. The centre frequency f_C is the arithmetic mean value of the upper and lower frequencies at the 3 dB filter attenuation level relative to the insertion loss a_e .

**) $\Delta f_C [\text{Hz}] = TC_f [\text{ppm/K}] \times (T[K] - T_0[K]) \times f_{T0} [\text{MHz}]$

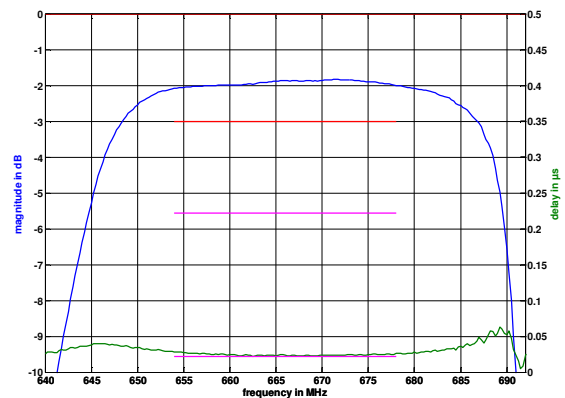
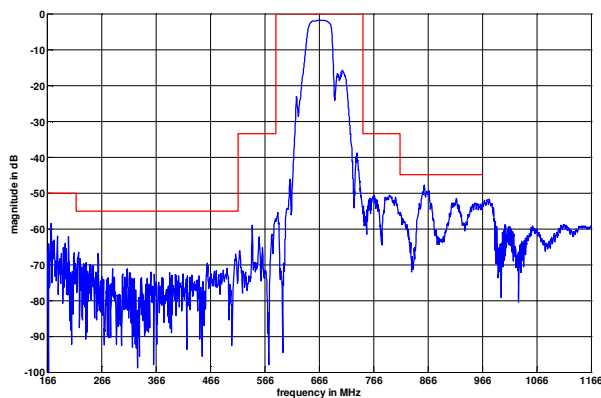
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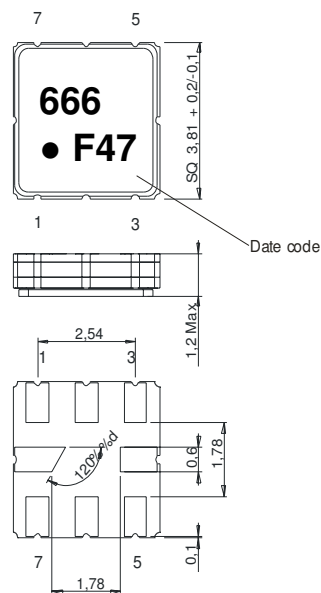
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Filter characteristic



Construction and pin connection

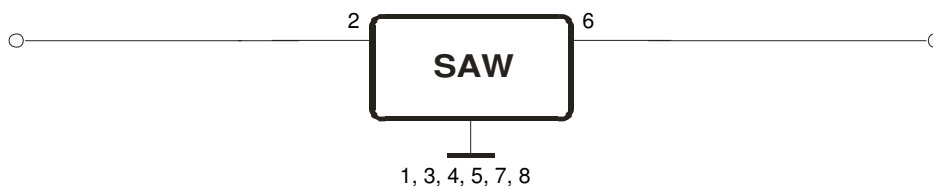
(All dimensions in mm)



1	Ground
2	Input
3	Ground
4	Ground
5	Ground
6	Output
7	Ground
8	Ground

Date code: Year + week
 F 2015
 G 2016
 H 2017
 ...

50 Ω Test circuit



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Stability characteristics, reliability

After the following tests the filter shall meet the whole specification:

1. Shock: 500 g, 1 ms, half sine wave, 3 shocks each plane;
DIN IEC 68 T2 - 27
2. Vibration: 10 Hz to 2000 Hz, 0.35 mm or 5 g respectively, 1 octave per min, 10 cycles per plane, 3 planes; DIN IEC 68 T2 - 6
3. Change of temperature: -55 °C to 125 °C / 15 min. each / 100 cycles
DIN IEC 68 part 2 – 14 Test N
4. Resistance to solder heat (reflow): reflow possible: three times max.;
for temperature conditions, see page 4: "Air reflow temperature conditions"
5. ESD: SAW devices are electrostatic discharge (ESD) sensitive devices

This filter is RoHS compliant (2011/65/EU)

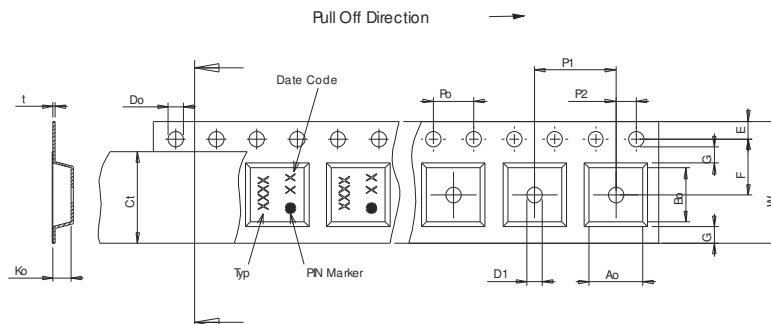
Packing

Tape & Reel: IEC 286 – 3, with exception of value for N and minimum bending radius;
tape type II, embossed carrier tape with top cover tape on the upper side;

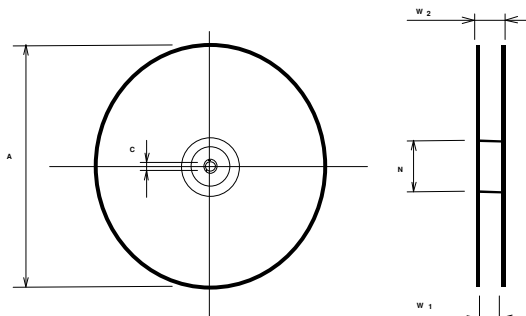
max. pieces of filters per reel:	3000
reel of empty components at start:	min. 300 mm
reel of empty components at start including leader:	min. 500 mm
trailer:	min. 300 mm

Tape (all dimensions in mm)

W	: 12,00 ± 0,3
Po	: 4,00 ± 0,1
Do	: 1,50 +0,1/-0
E	: 1,75 ± 0,1
F	: 5,50 ± 0,05
G(min)	: 0,75
P2	: 2,00 ± 0,05
P1	: 8,00 ± 0,1
D1(min)	: 1,50
Ao	: 4,30 ± 0,1
Bo	: 4,30 ± 0,1
Ct	: 9,5 ± 0,1

**Reel (all dimensions in mm)**

A	: 330 or 180
W1	: 12,4 +2/-0
W2(max)	: 18,4
N(min)	: 50
C	: 13,0 +0,5/-0,2



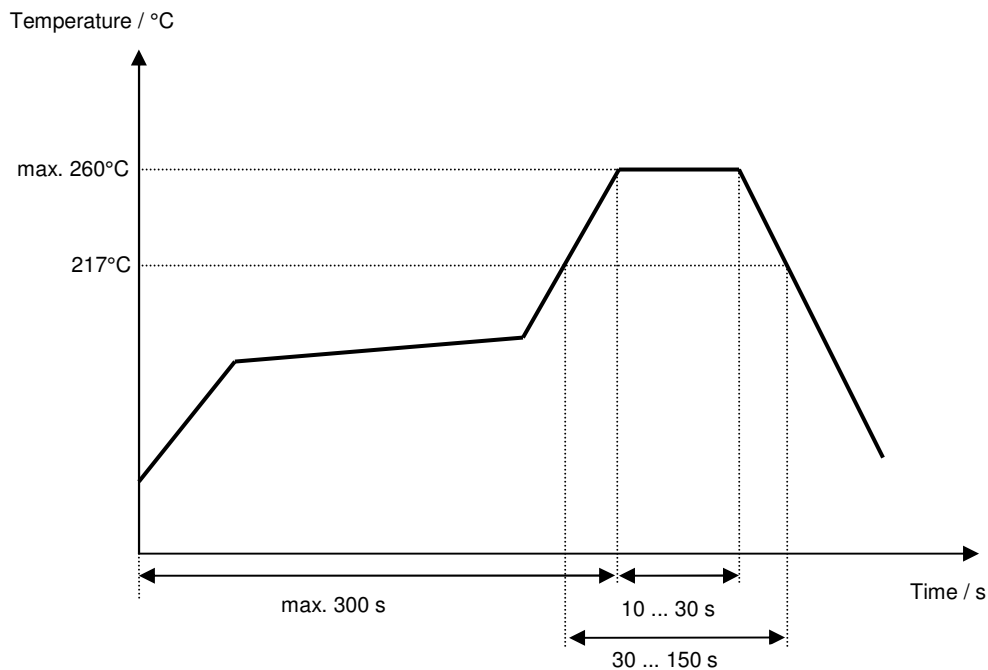
The minimum bending radius is 45 mm.

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Air reflow temperature conditions

Conditions	Exposure
Average ramp-up rate (30°C to 217°C)	less than 3°C/second
> 100°C	between 300 and 600 seconds
> 150°C	between 240 and 500 seconds
> 217°C	between 30 and 150 seconds
Peak temperature	max. 260°C
Time within 5°C of actual peak temperature	between 10 and 30 seconds
Cool-down rate (Peak to 50°C)	less than 6°C/second
Time from 30°C to Peak temperature	no greater than 300 seconds

Chip-mount air reflow profile

Vectron International**Filter specification****TFS 666****5/5****History**

Version	Reason of Changes	Name	Date
1.0	Generation of development specification	Springfeldt	14.04.2004
1.1	Adjust attenuation and loss to new customer requirements	Noack	26.11.2004
1.2	Adjust attenuation and loss to new customer requirements	Martens	29.11.2004
1.3	Change of absolute attenuation	Strehl	20.01.2005
1.4	Change stability characteristics Add typical values and filter characteristic Generation of filter specification	Strehl	04.05.2005
1.5	Add IIP3 and change stability characteristics	Strehl	19.07.2006
1.6	Maximum input power updated	Kortenbeutel	07.01.2014
1.7	Maximum input power updated Typos corrected	Molke	18.11.2015